21. A system, comprising:

a damper operable to provide a damping force in response to a reception of a first operating current; and

a controller,

wherein said controller is operable to generate a second operating current as a function of a desired force level of the damping force,

wherein said controller is operable to determine a scale factor and an offset value as a function of an operating temperature of the damper and a velocity of the damper, and

wherein said controller is operable to provide the first operating current to the damper in response to a determination of the scale factor and the offset value.

22. The system of claim 21, wherein

said controller is further operable to generate a third operating current as a product of the second operating current and the scale factor, and

said controller is further operable to generate the first operating current as a summation of the third operating current and the offset value.

23. The system of claim 21, wherein

said controller is further operable to generate a third operating current as a summation of the second operating current and offset value, and

said controller is further operable to generate the first operating current as a product of the third operating current and the scale factor.